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4. **STARETU, I.,** The Structure, Work Space and Direct Kinematic of the Robots with 8 Axes of Type T Normal R Parallel (PM)(OM), *Applied Mechanics and Materials* Vol 658 (2014) pp 718-723, © (2014) Trans Tech Publications, Switzerland, doi:10.4028/www.scientific.net/AMM.658.718.
5. **JITARIU, S., STARETU, I., MOLDOVAN, C.,** Robotized Montage Unit which Uses an Anthropomorphic Gripper with Five Fingers: CAD Modelling and Simulation, *Applied Mechanics and Materials* Vol 656 (2014) pp 146-153, © (2014) Trans Tech Publications, Switzerland, doi:10.4028/www.scientific.net/AMM.656.146.
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